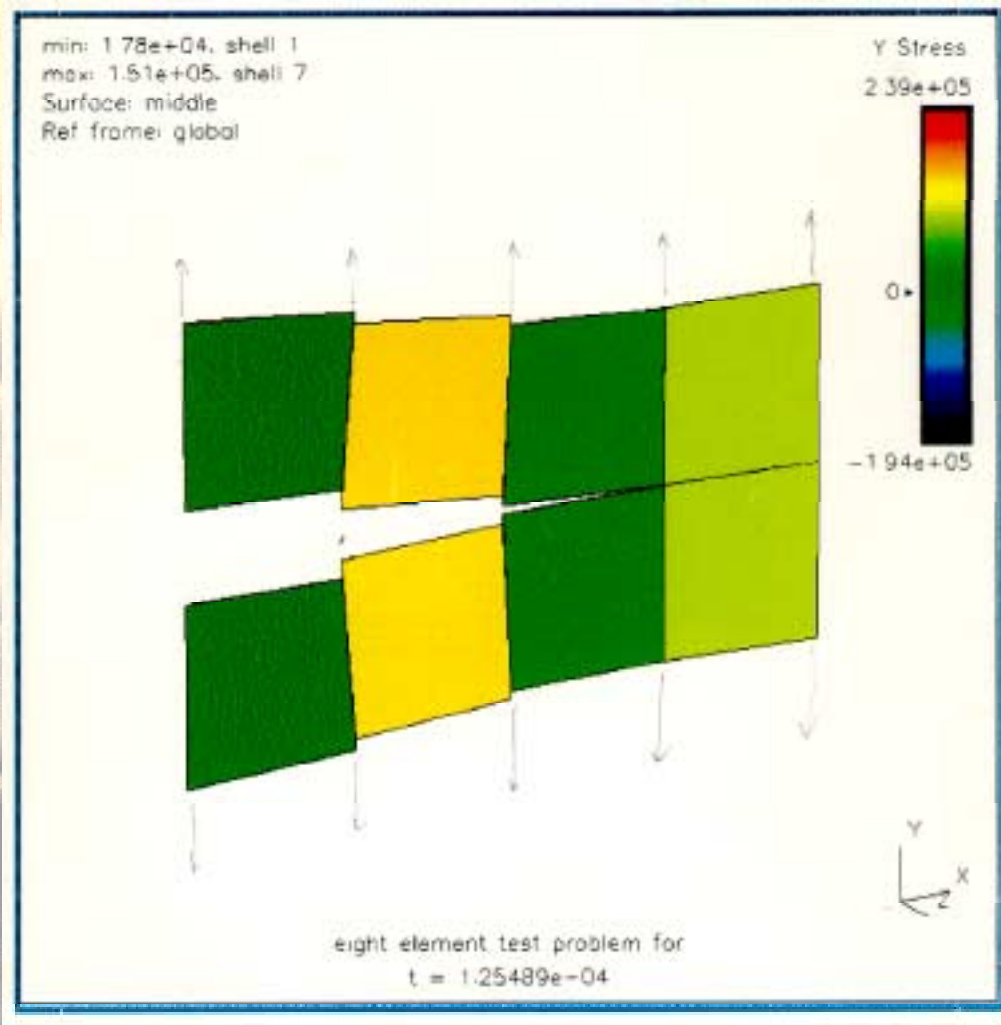

Modeling Fracture in High Explosives

Jobie Gerken

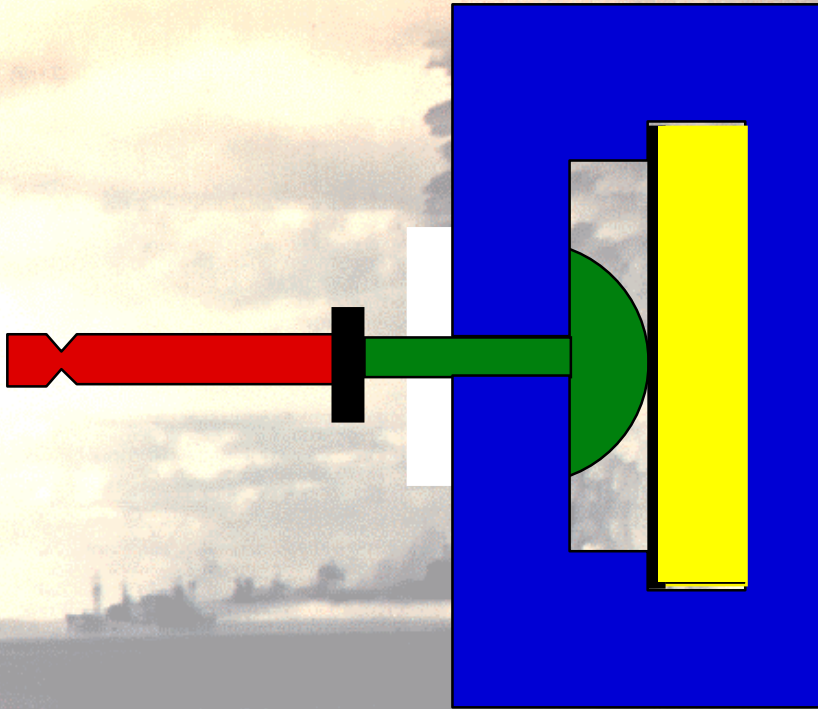
4 Years Ago



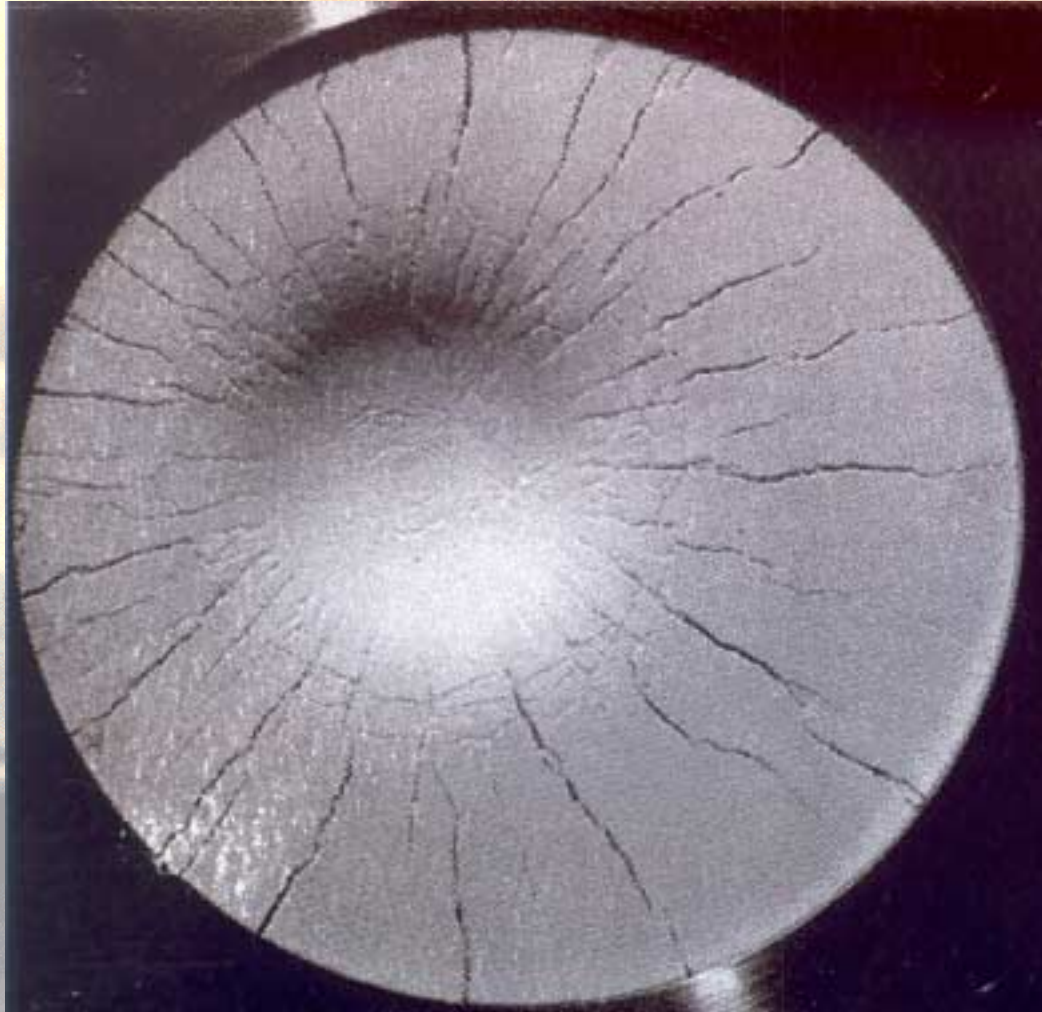
If you can't convince `em, confuse `em.

Harry S. Truman

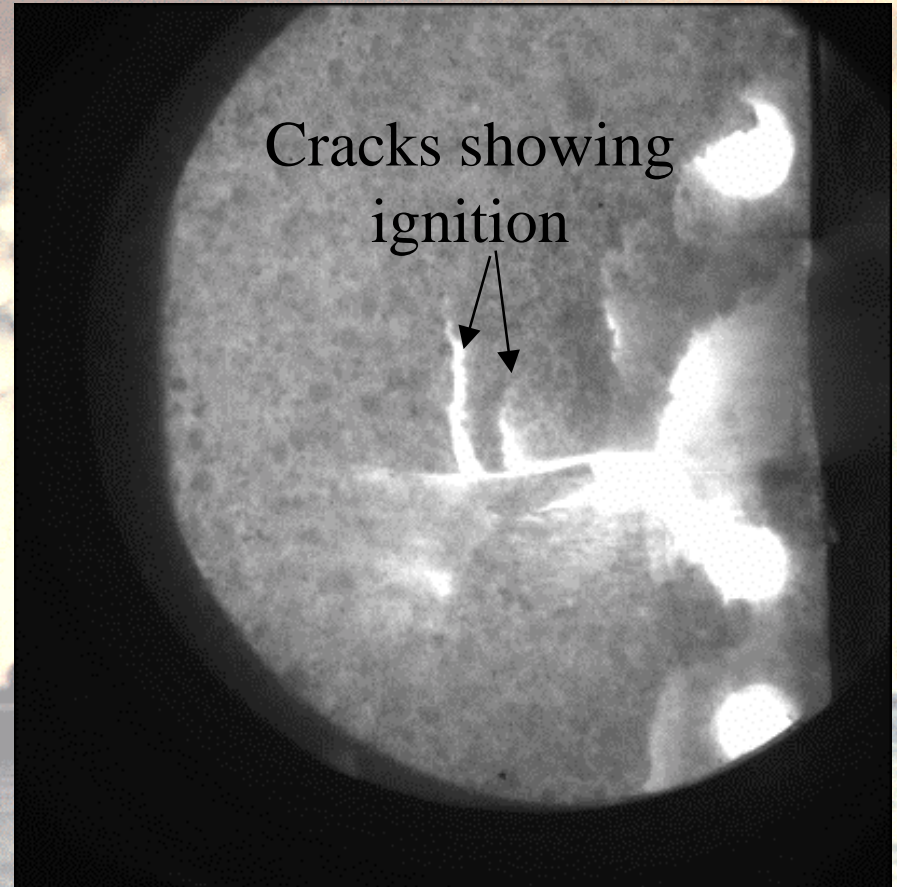
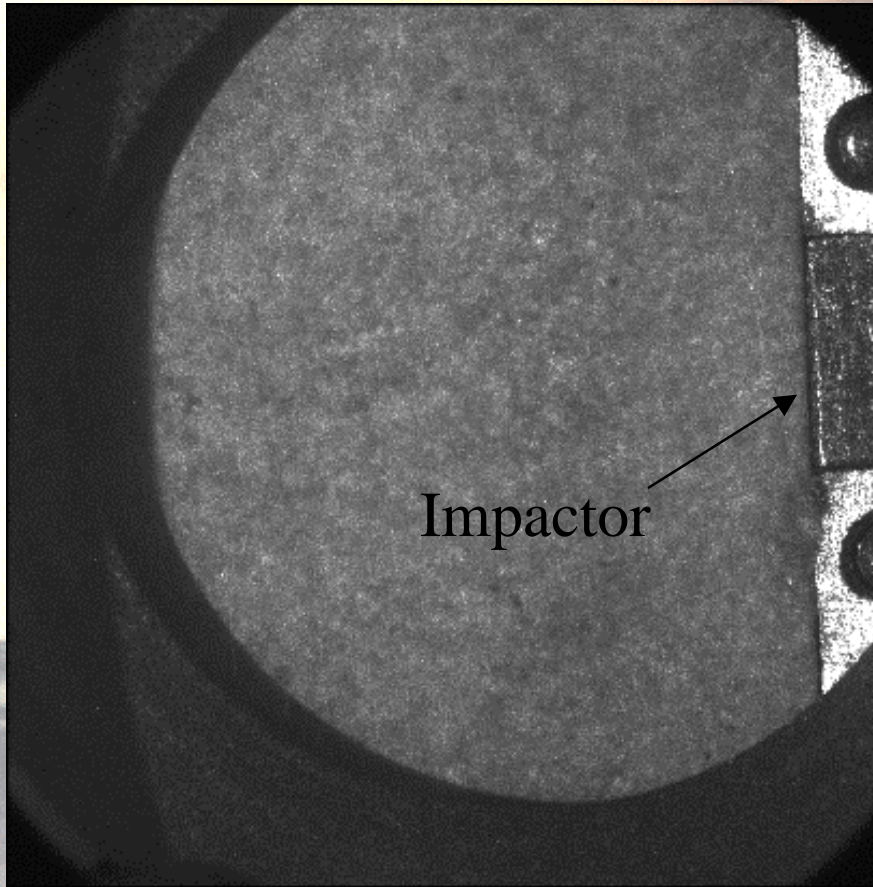
Why Model Fracture in HE?



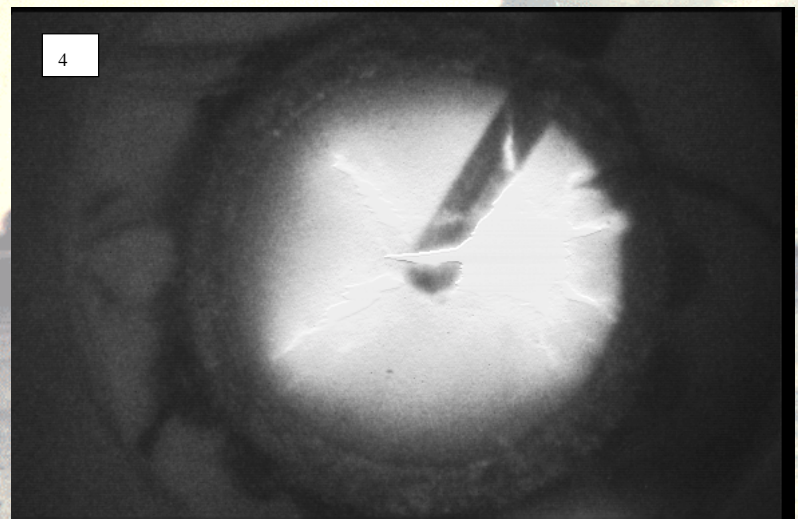
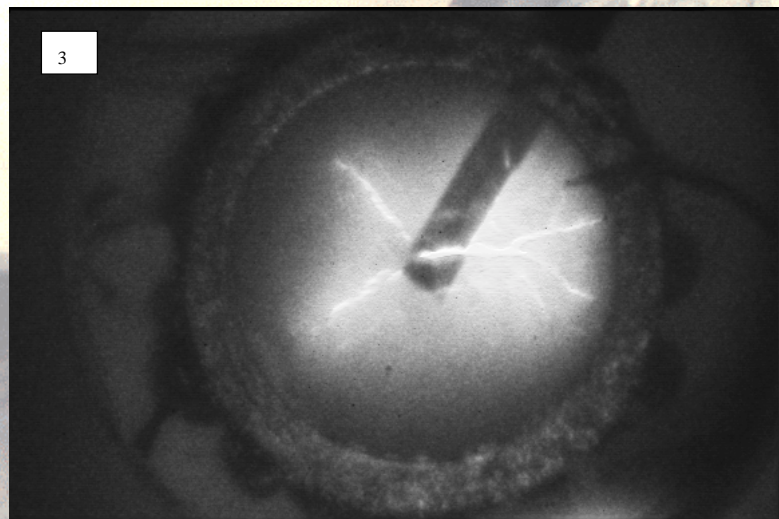
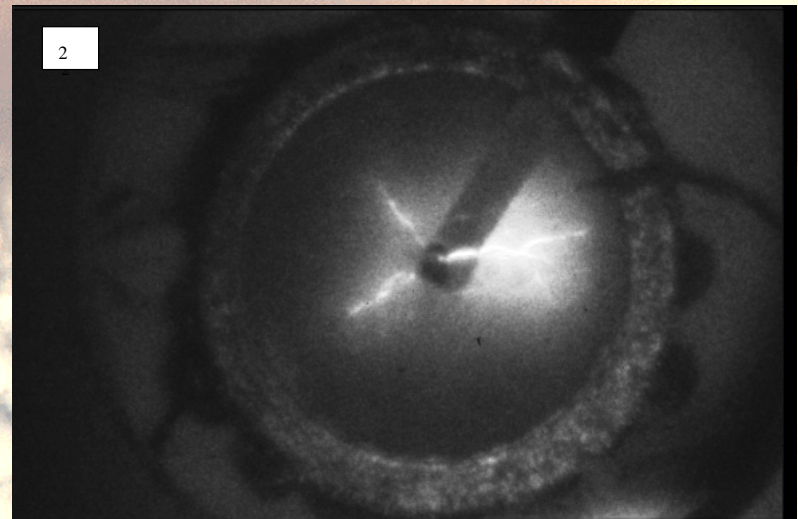
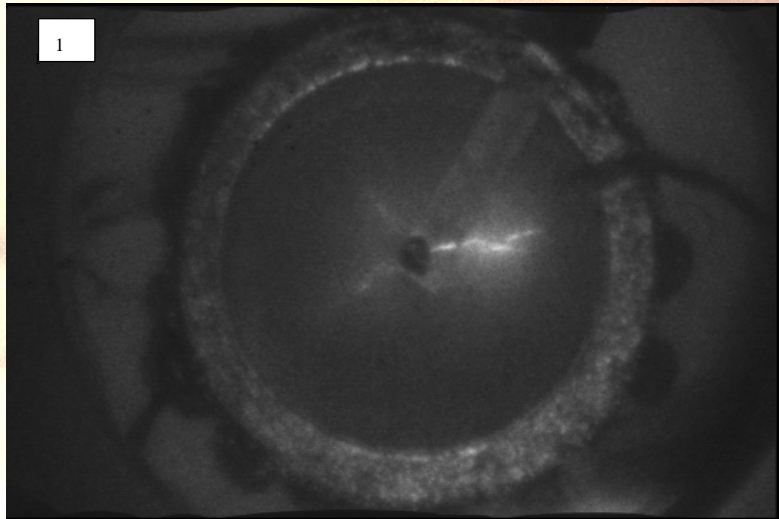
Why Model Fracture in HE?



Why Model Fracture in HE?



Why Model Fracture in HE?



Why Model Fracture in HE?

- It does happen
- STS environments
 - If HE cracks, someone would like to know
- Abnormal environments
 - HE reaction violence could be affected by fracture

How to Model Fracture in HE?

- Computation fracture methods are lacking
 - Finite element bias
 - Most popular structural analysis method
 - No accurate methods in current FE codes
 - Damage
 - Element deletion
 - Methods in development
 - Finite Element
 - Other computational methods coupled w/ FE

How to Model Fracture in HE?

- Linear elastic fracture is well characterized
- HE is not well behaved
 - Particulate composite
 - Polymer component
 - Rate dependent
 - Not linear elastic fracture!
- Need fracture criteria for HE

Fracture Modeling

- Goodman, R. E., Taylor, R. L., Brekke, T. L., 1968 “ A Model for the Mechanics of Jointed Rock,” *Proceedings of the ASCE: Journal of the Soil Mechanics and Foundations Division*, Vol. 98, pp. 637-659.
- Liaw, B. M., Kobayashi, A. S., Emery, A. F., 1984, “Double Noding Technique for Mixed Mode Crack Propagation Studies,” *International Journal For Numerical Methods in Engineering*, Vol. 20, pp. 967-977.
- Xu, X. P., Needleman, A., 1994, “Numerical Simulations of Fast Crack Growth in Brittle Solids,” *Journal of the Mechanics and Physics of Solids*, Vol. 42, pp. 1397-1434.
- Belytschko, T., Lu, Y. Y., Gu, L., 1995, “Crack Propagation by Element-Free Galerkin Methods,” *Engineering Fracture Mechanics*, Vol. 51, pp. 295-315.

Problems with Current Methods

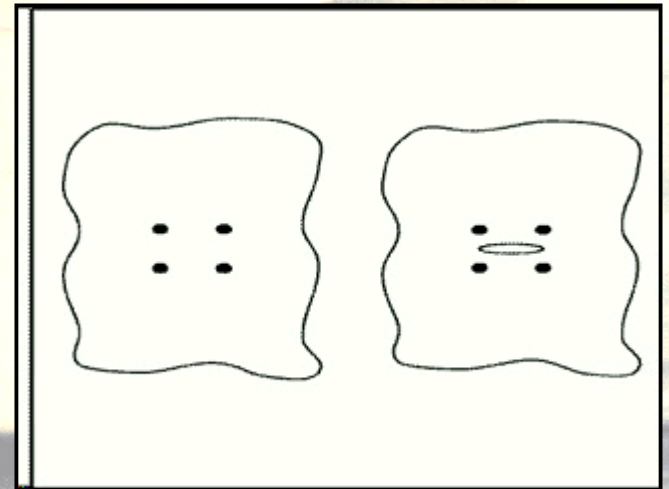
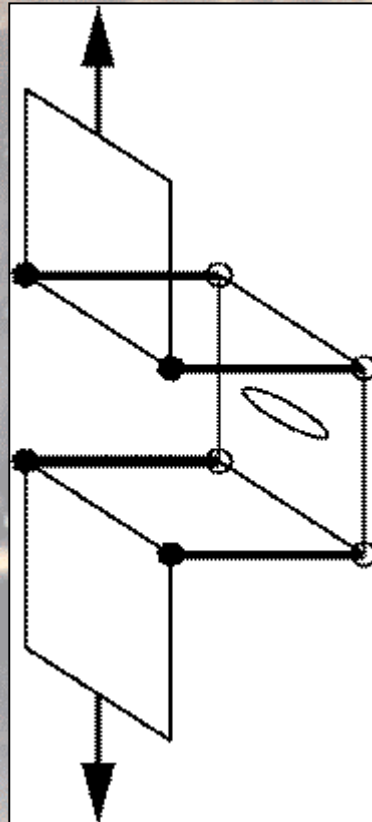
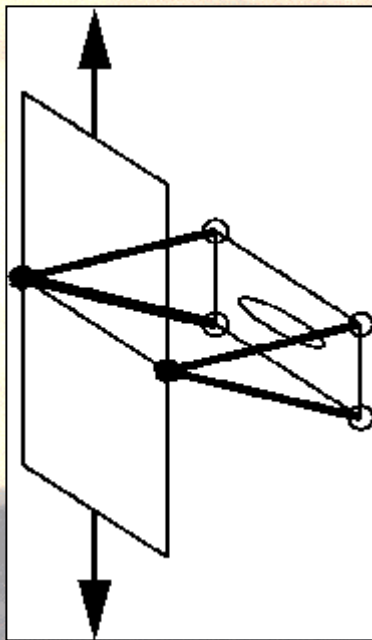
- Not applicable to structural scale models
 - Accurate when FE size \sim process zone size
 - No quick / easy fracture criteria
- No easy framework for implementation
 - Not in commercial codes
 - User written

Our Fracture Method

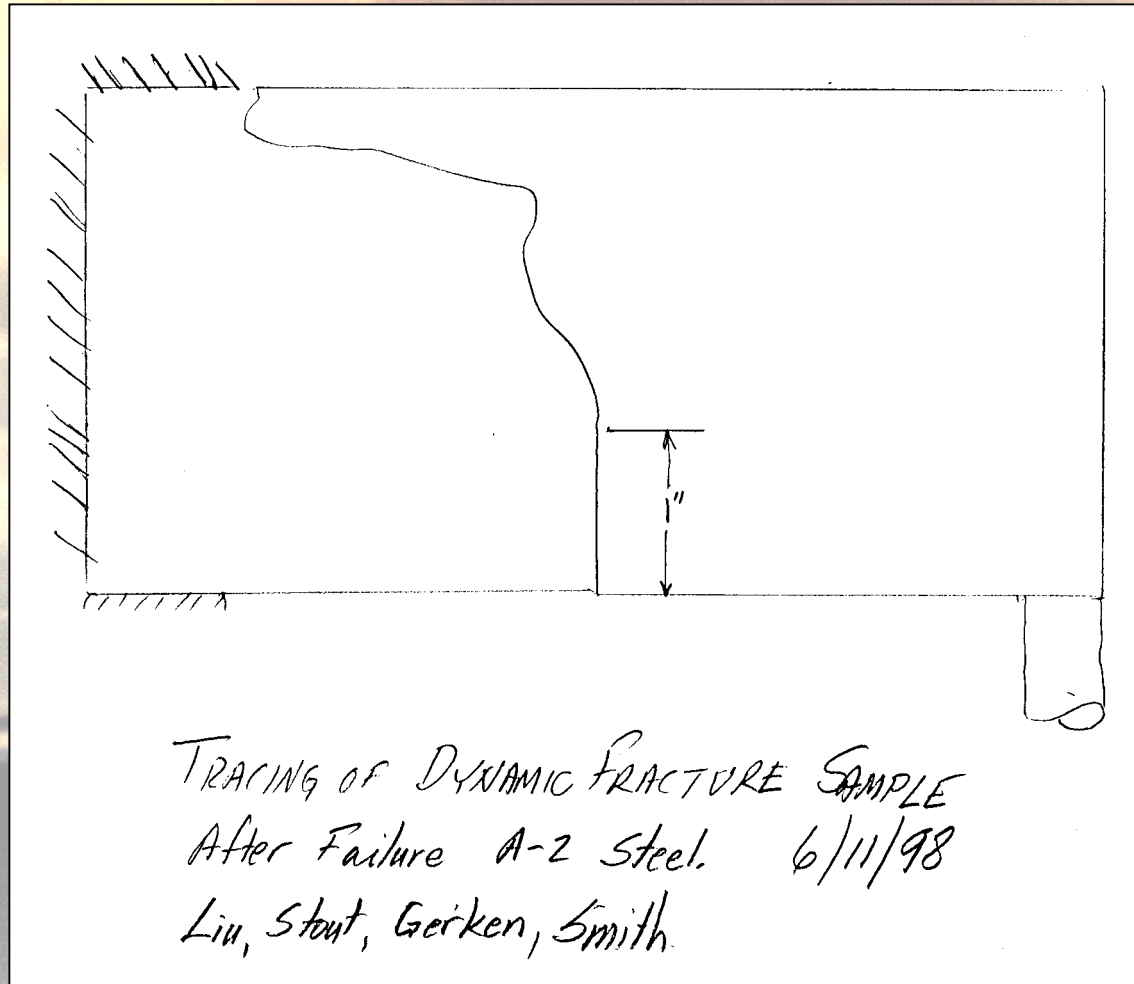
- Rigid and deformable interface models
- 2-dimensional
 - Implicit - ABAQUS/Standard
 - Explicit - DYNA3D - plates
- 3-dimensional
 - Explicit - DYNA3D - bricks

DYNA3D 2-D Model

- Virtual Finite Element



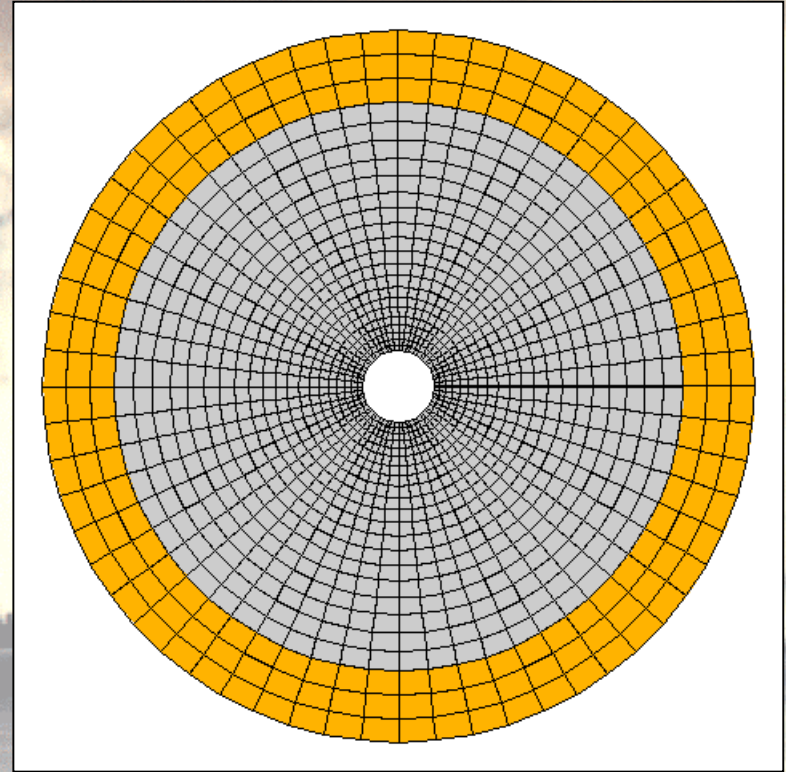
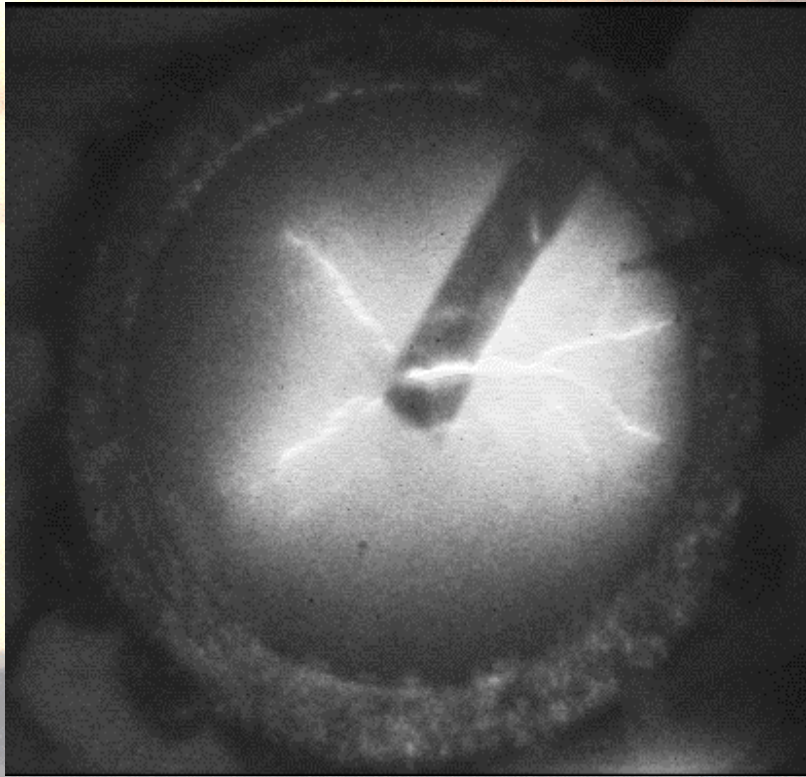
2-D Success - Steel



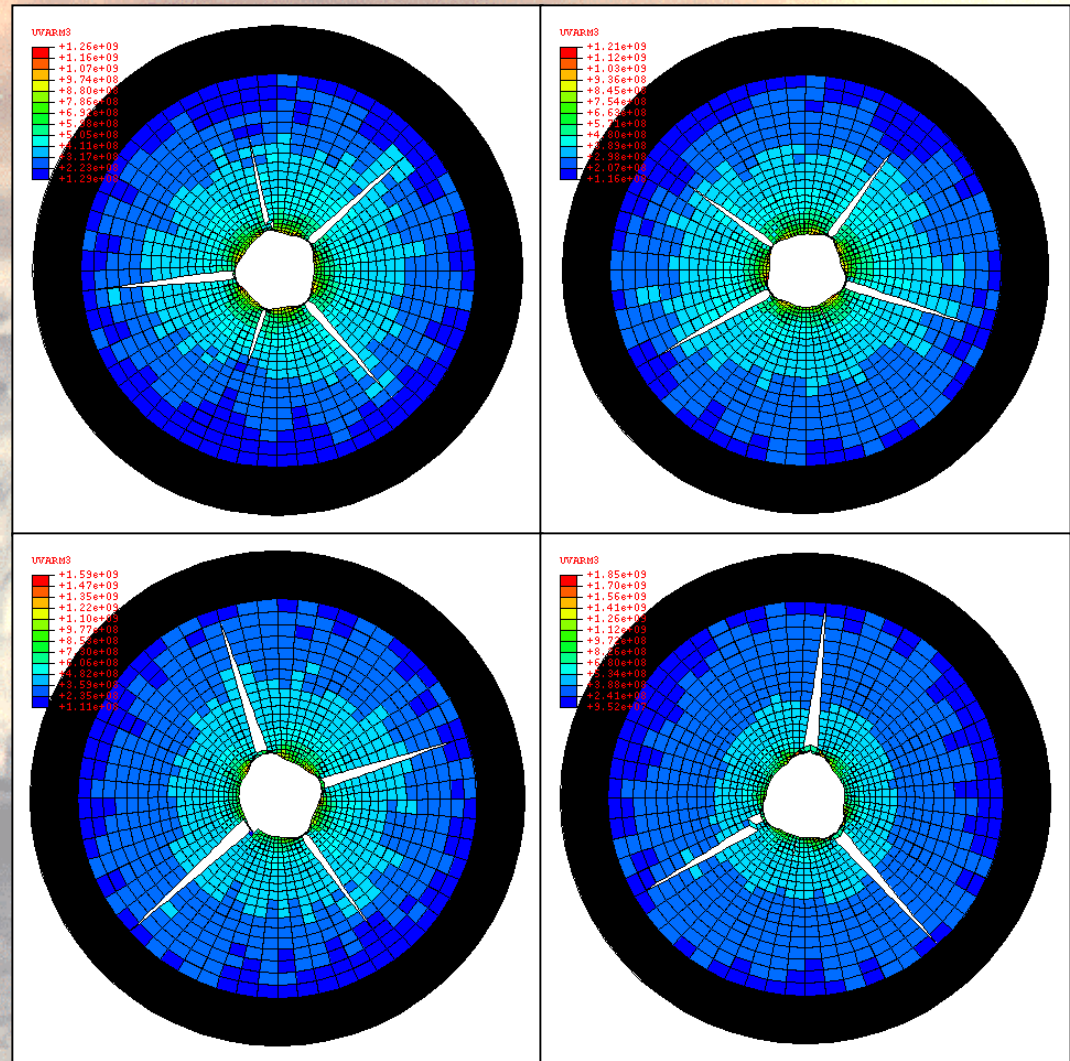
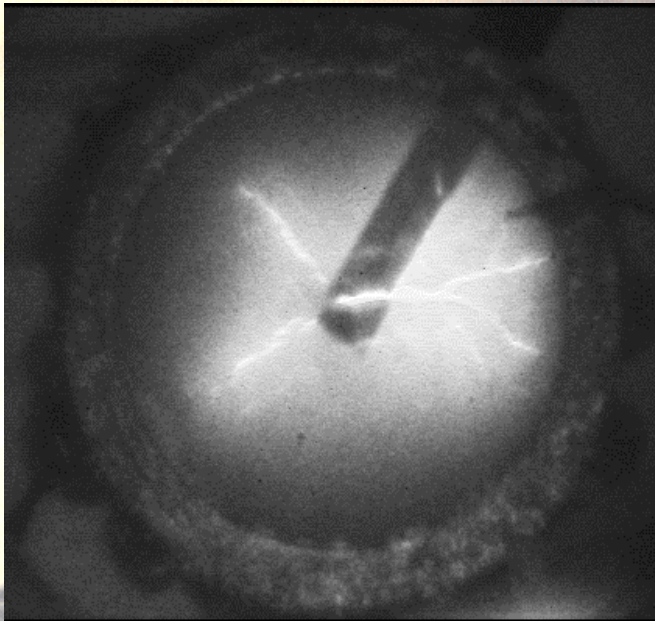
2-D Success - Steel



2-D Success - HE



2-D Success - HE



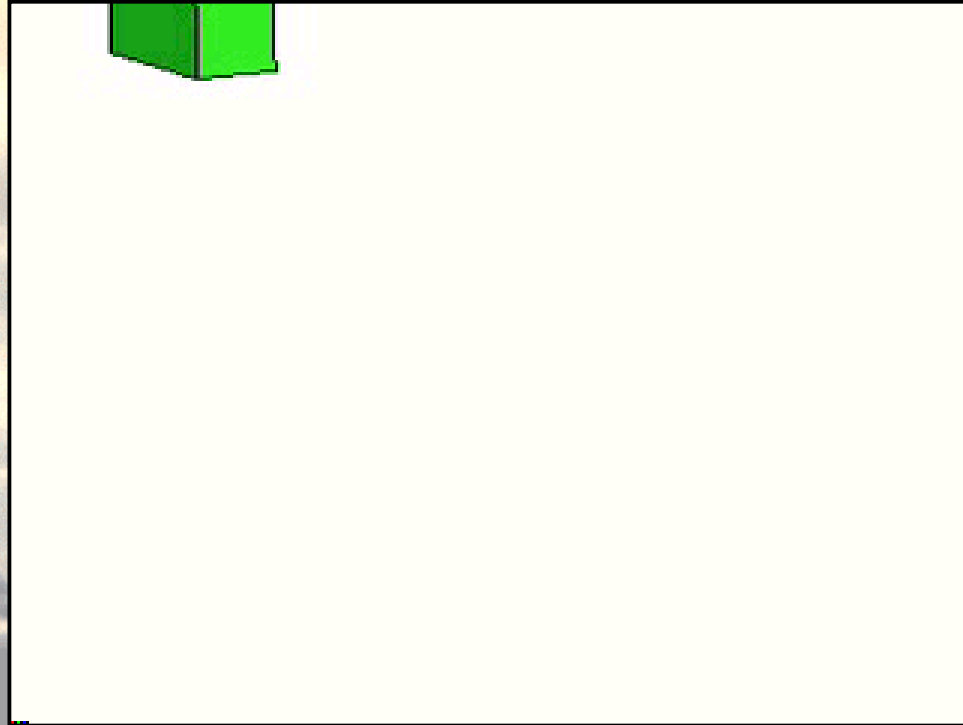
2-D Problems

- Implicit FEA is very slow
 - Fracture tends to happen on explicit time scale
- VFE would not quite work
 - Known problems we didn't want to deal with
- Contact for new crack surfaces is difficult
- Most things are not 2-D

Increase Your Dimensionality

- 3 Dimensions
 - DYNA3D
 - Each element is unique - building blocks
 - Rigid interfaces - Displacement continuity
 - Interface failure = no displacement continuity
 - Use DYNA3D auto-contact
 - New crack surface is a new contact surface

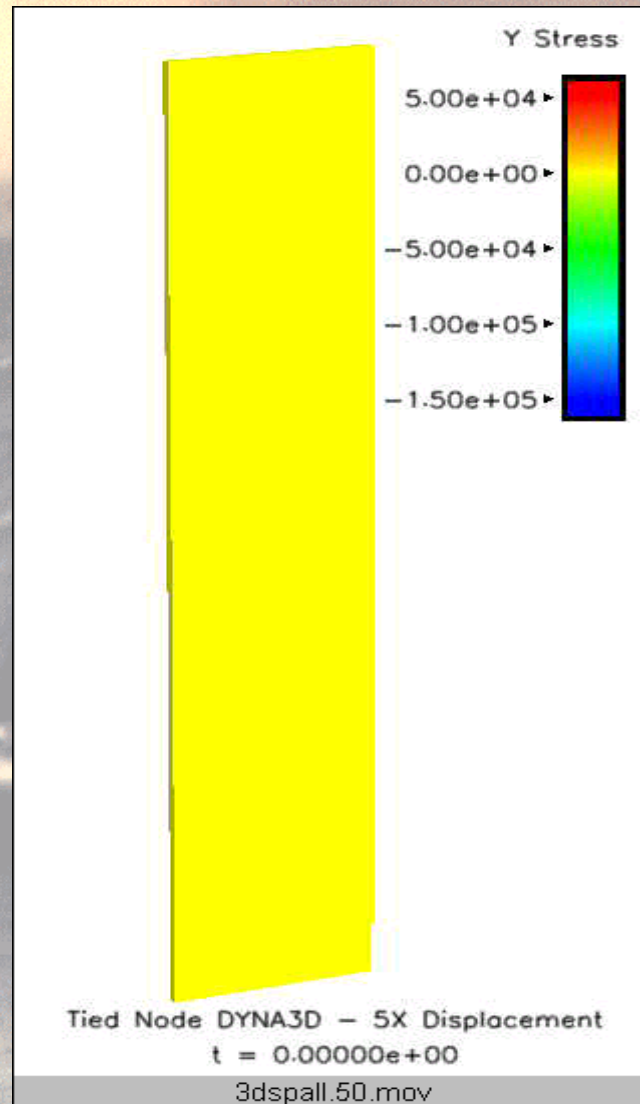
3 Dimensions



3 Dimensional Advantages

- Incorporated into DYNA3D Code
 - 1 Flag in input deck
 - 1 line of fracture parameters
- Internal to the code
 - Redefine mesh
 - Ensure displacement continuity
 - Modifies contact surface definition to include new crack surface
 - Evaluate failure
 - provides testbed for failure criteria

3-D Success? - Steel

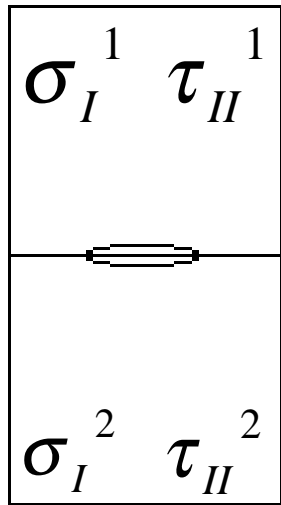


Failure Criteria

- This is the crux of the whole problem
- Fracture/failure criteria
 - Reproduce fracture/failure behavior
 - Evaluate on the local scale
 - “Normal” element sizes

Fracture Mechanics

- Small Crack at element interface

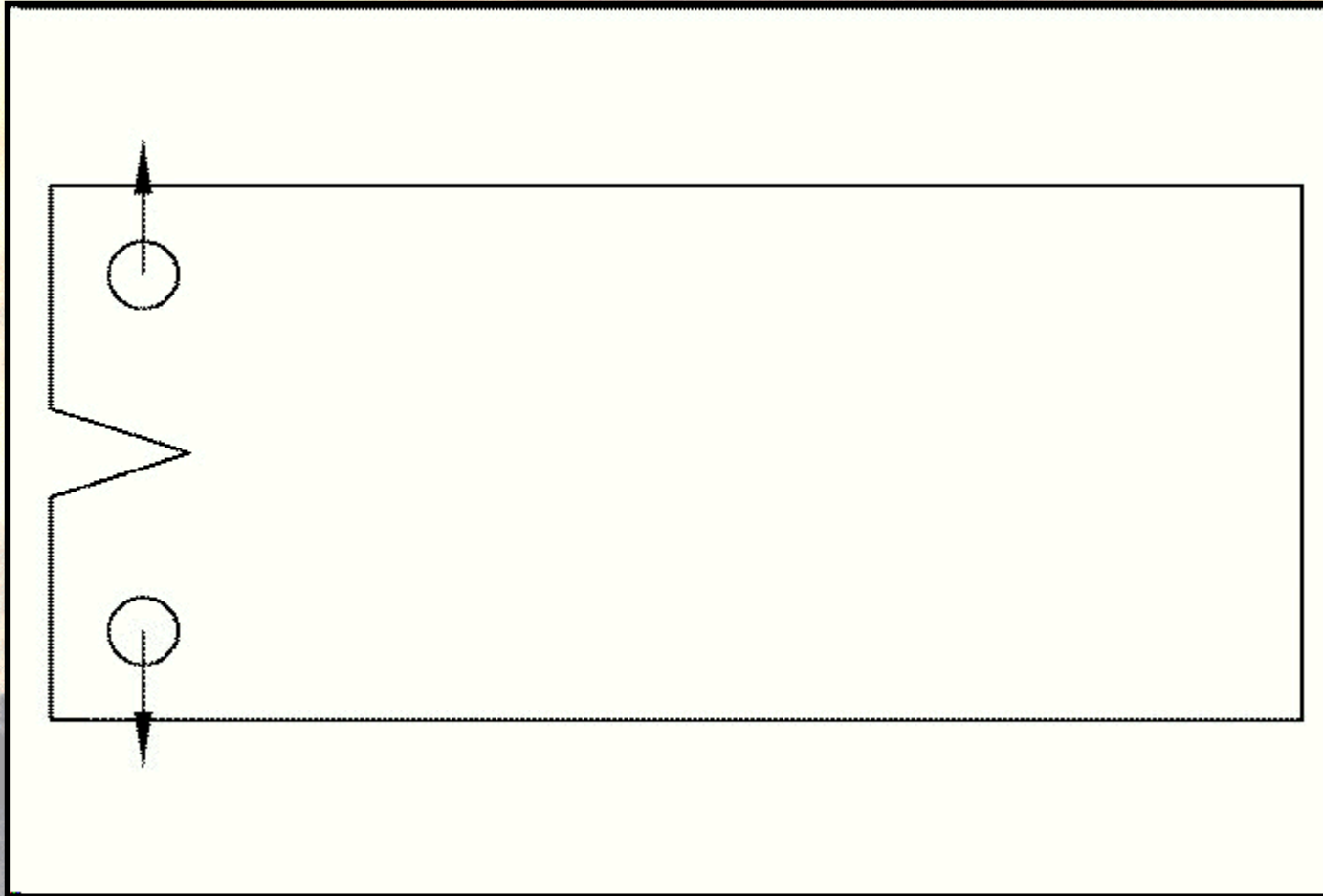


$$K_I = \sigma_I \sqrt{\pi \cdot a} \quad K_{II} = \tau_{II} \sqrt{\pi \cdot a}$$

$$G = \frac{K_I^2 + K_{II}^2}{E}$$

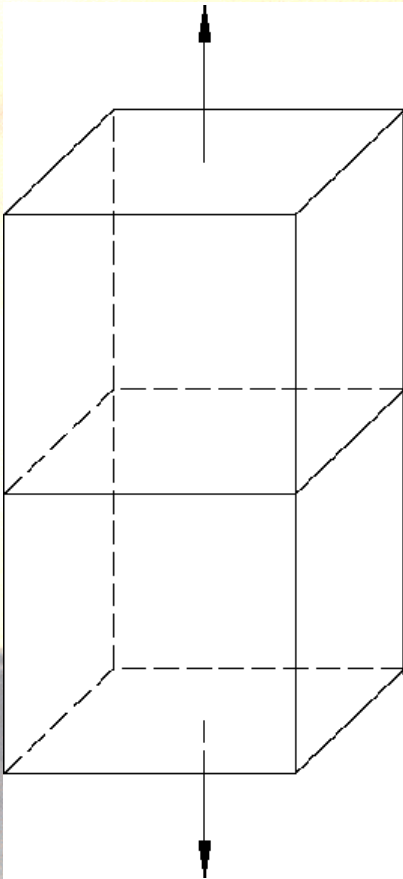
$$G = \beta (\Delta a)^\gamma + \lambda \quad \Delta a = \left(\frac{G - \lambda}{\beta} \right)^{\frac{1}{\gamma}}$$

HE Fracture



Bridging Now

- ViscoSCRAM bridging law

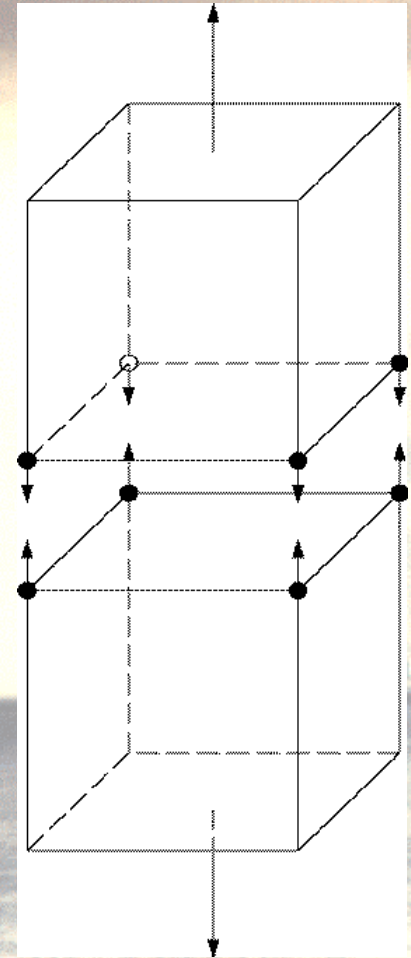


- Disp. continuity until critical stress

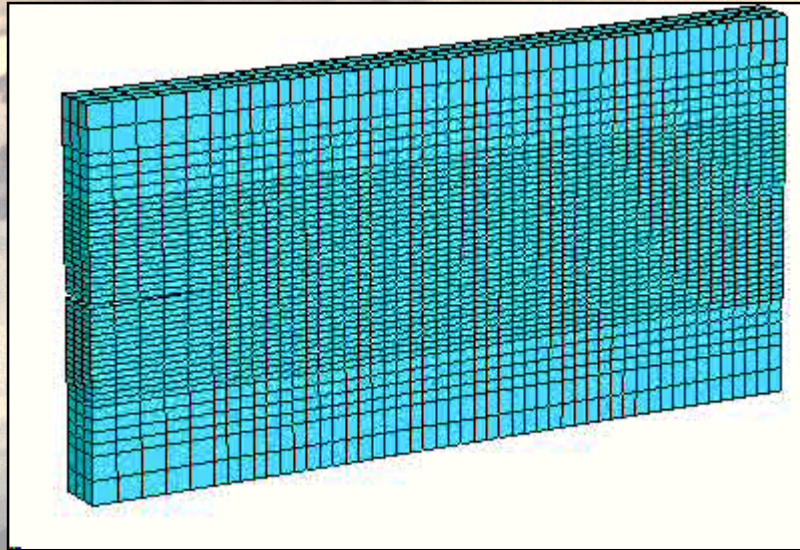
- Apply forces to nodes

- Now: $F(\sigma_{vs}, A)$

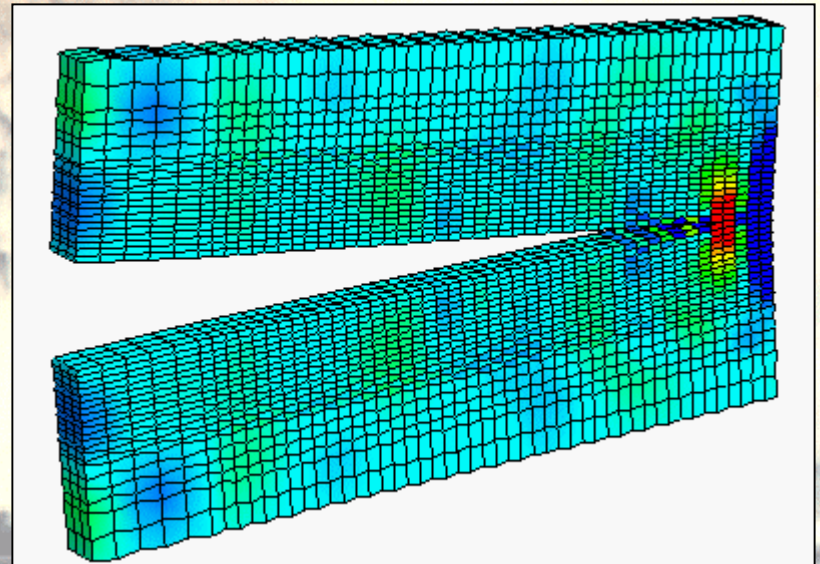
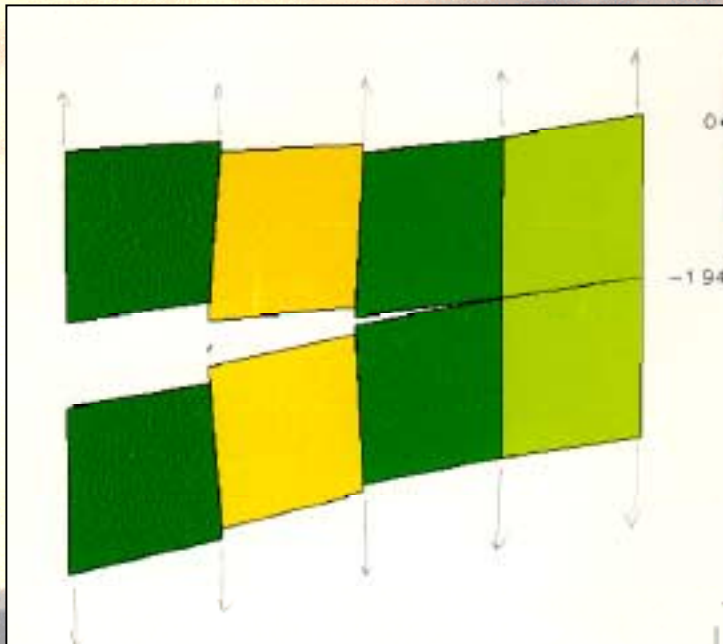
- Future: $F(\sigma_{vs}, A, \delta, \dot{\delta}, \epsilon, \dot{\epsilon}, L, \dots)$



Bridging Success



4 Years of Work



The Future of HE Fracture

- Stress Bridging
- HE decomposition / gas evolution / crack face burning
- DYNA3D production release?